SGM7G

SGM7G	-	05	D	F	F	6	F	
Sigma-7 Series Servomotors: SGM7G		1st + 2nd	3rd	4th	5th	6th	7th	digit

1st + 2nd digit - Rated Output	
Code	**Specification**
05	**450 W**
09	**850 W**
13	**1.3 kW**
20	**1.8 kW**
30	**2.9 kW**
44	**4.4 kW**
55	**5.5 kW**
75	**7.5 kW**
1A	**11.0 kW**
1E	**15.0 kW**

3rd digit - Power Supply Voltage	
Code	**Specification**
D	**400 VAC**

4th digit - Serial Encoder	
Code	**Specification**
7	24-bit absolute
F	**24-bit incremental**

5th digit - Design Revision Order	
Code	**Specification**
F	**Standard Model**
R*2	High-speed Model

6th digit - Shaft End	
Code	**Specification**
2	Straight without key (450 W, 1.8 kW, 2.9 kW)
6	**Straight with key and tap (450 W, 1.8 kW, 2.9 kW)**
S*1	Straight without key (850 W, 1.3 kW)
K*1	**Straight with key and tap (850 W, 1.3 kW)**

7th digit - Options	
Code	**Specification**
1	Without options
C	With holding brake (24 VDC)
F	**With dust seal**
H	With dust seal and holding brake (24 VDC)

*1 The shaft end codes are different for 850 kW and 1.3 kW Servomotors.
The shaft diameter for 850 W Servomotors is 19 mm.
The shaft diameter for 1.3 kW Servomotors is 22 mm.
*2 Available up to 4.4 kW.

Bolded options are considered standard warehouse products.

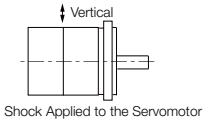
Specifications and Ratings

Specifications

Voltage			400 V									
Model SGM7G-			**05D**	**09D**	**13D**	**20D**	**30D**	**44D**	**55D**	**75D**	**1AD**	**1ED**
Time Rating			Continuous									
Thermal Class			F									
Insulation Resistance			500 VDC, 10 MΩ min.									
Withstand Voltage			1,800 VAC for 1 minute									
Excitation			Permanent magnet									
Mounting			Flange-mounted									
Drive Method			Direct drive									
Rotation Direction			Counterclockwise (CCW) for forward reference when viewed from the load side									
Vibration Class*1			V15									
Environmental Conditions	Surrounding Air Temperature		0 °C to 40 °C (With derating, usage is possible between 40 °C and 60 °C)*4									
	Surrounding Air Humidity		20% to 80% relative humidity (with non-condensing)									
	Installation Site		• Must be indoors and free of corrosive and explosive gases. • Must be well-ventilated and free of dust and moisture. • Must facilitate inspection and cleaning. • Must have an altitude of 1,000 m or less. (With derating, usage is possible between 1,000 m and 2,000 m.)*5 • Must be free of strong magnetic fields.									
	Storage Environment		Store the Servomotor in the following environment if you store it with the power cable disconnected. Storage Temperature: -20 °C to 60 °C (with no freezing) Storage Humidity: 20 % to 80% relative humidity (non-condensing)									
Shock Resistance*2	Impact Acceleration Rate at Flange		490 m/s²									
	Number of Impacts		2 times									
Vibration Resistance*3	Vibration Acceleration Rate at Flange		49 m/s² (24.5 m/s² front to back)						24.5 m/s²			
Applicable SERVOPACKs	When using a Standard Servomotor	SGD7S-	1R9D	3R5D	5R4D	8R4D	120D	170D	210D	260D	280D	370D
		SGD7W-	2R6D*6 or 5R4D*6	5R4D*6	5R4D				–			
	When using a High-speed Servomotor	SGD7S-	3R5D	5R4D	8R4D	120D	170D	210D	–			
		SGD7W-	2R6D or 5R4D*6	5R4D	–							

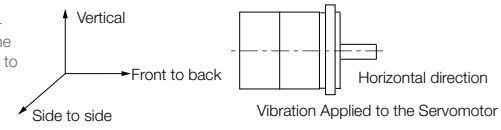
*1. A vibration class of V15 indicates a vibration amplitude of 15 μm maximum on the Servomotor without a load at the rated motor speed.

*2. The shock resistance for shock in the vertical direction when the Servomotor is mounted with the shaft in a horizontal position is given in the above table.



Shock Applied to the Servomotor

*3. The vertical, side-to-side, and front-to-back vibration resistance for vibration in three directions when the Servomotor is mounted with the shaft in a horizontal position is given in the above table. The strength of the vibration that the Servomotor can withstand depends on the application. Always check the vibration acceleration rate that is applied to the Servomotor with the actual equipment.



Vibration Applied to the Servomotor

*4. If the surrounding air temperature will exceed 40°C, refer to the section “Applications where the Surrounding Air Temperature of the Servomotor Exceeds 40°C”.

*5. If the altitude will exceed 1,000 m, refer to the section “Applications where the Altitude of the Servomotor Exceeds 1000m”.

*6. If you use this combination, performance may not be as good, e.g., the control gain may not increase, in comparison with using a Sigma-7S SERVOPACK.

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Servomotor Ratings

Standard Servomotors

Voltage			400 V									
Model SGM7G-			05D	09D	13D	20D	30D	44D	55D	75D	1AD	1ED
Rated Output *1		kW	0.45	0.85	1.3	1.8	2.9	4.4	5.5	7.5	11	15
Rated Torque *1, *2		Nm	2.86	5.39	8.34	11.5	18.6	28.4	35.0	48.0	70.0	95.4
Instantaneous Maximum Torque *1		Nm	8.92	13.8	23.3	28.7	45.1	71.6	87.6	119	175	224
Rated Current *1		A	1.9	3.5	5.4	8.4	11.9	16	20.8	25.7	28.1	37.2
Instantaneous Maximum Current *1		A	5.5	8.5	14	20	28	40.5	52	65	70	85
Rated Motor Speed *1		min^{-1}	1,500									
Maximum Motor Speed *1		min^{-1}	3,000								2,000	
Torque Constant		Nm/A	1.71	1.72	1.78	1.50	1.70	1.93	1.80	1.92	2.76	2.86
Motor Moment of Inertia		$\times 10^{-4}$ kg m^2	3.33 (3.58)	13.9 (16.0)	19.9 (22.0)	26.0 (28.1)	46.0 (53.9)	67.5 (75.4)	89 (96.9)	125 (133)	242 (261)	303 (341)
Rated Power Rate *1		kW/s	24.6 (22.8)	20.9 (18.2)	35.0 (31.6)	50.9 (47.1)	75.2 (64.2)	119 (107)	138 (126)	184 (173)	202 (188)	300 (267)
Rated Angular Acceleration Rate *1		rad/s^2	8,590 (7,990)	3,880 (3,370)	4,190 (3,790)	4,420 (4,090)	4,040 (3,450)	4,210 (3,770)	3,930 (3,610)	3840 (3,610)	2,890 (2,680)	3,150 (2,800)
Heat Sink Size		mm	250 × 250 × 6 (aluminium)	400 × 400 × 20 (steel)			550 × 550 × 30 (steel)				650 × 650 × 35 (steel)	
Protective Structure *3			Totally enclosed, self-cooled, IP67									
Holding Brake Specifications *4	Rated Voltage	V	24 VDC 0 / +10%									
	Capacity	W		10			18.5		25		32	35
	Holding Torque	Nm	4.5	12.7	19.6		43.1		72.6		84.3	114.6
	Coil Resistance	Ω (at 20 °C)	56	59			31		23		18	17
	Rated Current	A (at 20 °C)	0.43	0.41			0.77		1.05		1.33	1.46
	Time Required to Release Brake	ms	100						170			250
	Time Required to Brake	ms	80				100		80			
Allowable Load Moment of Inertia (Motor Moment of Inertia Ratio)	Standard		15 times	5 times					10 times			
	With External Regenerative Resistor and Dynamic Brake Resistor Connected		15 times	10 times								
Allowable Shaft Load *5	LF	mm	40	58			79		113		116	
	Allowable Radial Load	N	490		686	980	1,470		1,764			4,998
	Allowable Thrust Load	N	98		343	392	490		588			2,156

Note:
The values in parentheses are for Servomotors with Holding Brakes.

*1. These values are for operation in combination with a SERVOPACK when the temperature of the armature winding is 20°C. These are typical values.

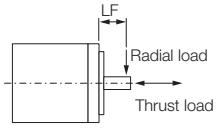
*2. The rated torques are the continuous allowable torque values at a surrounding air temperature of 40°C with an aluminum or steel heat sink of the dimensions given in the table.

*3. This does not apply to the shaft opening. Protective structure specifications apply only when the special cable is used.

*4. Observe the following precautions if you use a Servomotor with a Holding Brake.

- The holding brake cannot be used to stop the Servomotor.
- The time required to release the brake and the time required to brake depend on which discharge circuit is used. Confirm that the operation delay time is appropriate for the actual equipment.
- The 24-VDC power supply is not provided by YASKAWA.

*5. The allowable shaft loads are illustrated in the following figure. Design the mechanical system so that the thrust and radial loads applied to the Servomotor shaft end during operation do not exceed the values given in the table.



High-speed Servomotors

Voltage			400 V					
Model SGM7G-			05D	09D	13D	20D	30D	44D
Rated Output *1		kW	0.45	0.85	1.3	1.8	2.9	4.4
Rated Torque *1, *2		Nm	2.86	5.39	8.34	11.5	18.6	28.4
Instantaneous Maximum Torque *1		Nm	8.8	15	22	28.7	50.0	71.1
Rated Current *1		A	2.6	5.3	8.3	10.1	14.4	19.3
Instantaneous Maximum Current *1		A	8.2	14	21	24	40	50
Rated Motor Speed *1		min^{-1}	1,500					
Maximum Motor Speed *1		min^{-1}	5,000				4,500	
Allowable Continuous Motor Speed		min^{-1}	5,000	4,000			3,300	3,000
Torque Constant		Nm/A	1.13	1.12	1.09	1.27	1.36	1.58
Motor Moment of Inertia		$\times 10^{-4}$ kgm^2	3.33 (3.58)	13.9 (16)	19.9 (22)	26 (28.1)	46.0 (53.9)	67.5 (75.4)
Rated Power Rate *1		kW/s	24.6 (22.8)	20.9 (18.2)	35 (31.6)	50.9 (47.1)	75.2 (64.2)	119 (107)
Rated Angular Acceleration Rate *1		rad/s^2	8,590 (7,990)	3,880 (3,370)	4,190 (3,790)	4,420 (4,090)	4,040 (3,450)	4,210 (3,770)
Heat Sink Size		mm	250 × 250 × 6 (aluminium)	400 × 400 × 20 (steel)				
Protective Structure *3			Totally enclosed, self-cooled, IP67					
Holding Brake Specifications *4	Rated Voltage	V	24 VDC 0 / +10%					
	Capacity	W	10				18.5	
	Holding Torque	Nm	4.5	12.7	19.6		43.1	
	Coil Resistance	Ω (at 20 °C)	56	59			31	
	Rated Current	A (at 20 °C)	0.43	0.41			0.77	
	Time Required to Release Brake	ms	100				170	
	Time Required to Brake	ms	80				100	
Allowable Load Moment of Inertia (Motor Moment of Inertia Ratio)	Standard		8 times	2 times	4 times	3 times	2 times	5 times
	With External Regenerative Resistor and Dynamic Brake Resistor Connected		15 times	4 times	7 times	6 times	6 times	
Allowable Shaft Loads *5	LF	mm	40		58		79	
	Allowable Radial Load	N	490		686	980	1,470	
	Allowable Thrust Load	N	98		343	392	490	

Note:
The values in parentheses are for Servomotors with Holding Brakes.

*1. These values are for operation in combination with a SERVOPACK when the temperature of the armature winding is 20°C. These are typical values.

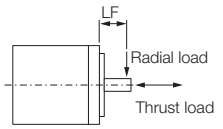
*2. The rated torques are the continuous allowable torque values at a surrounding air temperature of 40°C with an aluminum or steel heat sink of the dimensions given in the table.

*3. This does not apply to the shaft opening. Protective structure specifications apply only when the special cable is used.

*4. Observe the following precautions if you use a Servomotor with a Holding Brake.

- The holding brake cannot be used to stop the Servomotor.
- The time required to release the brake and the time required to brake depend on which discharge circuit is used. Confirm that the operation delay time is appropriate for the actual equipment.
- The 24-VDC power supply is not provided by YASKAWA.

*5. The allowable shaft loads are illustrated in the following figure. Design the mechanical system so that the thrust and radial loads applied to the Servomotor shaft end during operation do not exceed the values given in the table.

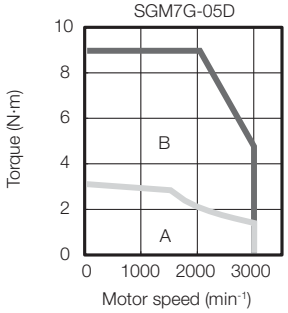


Motor Speed-Torque Characteristics

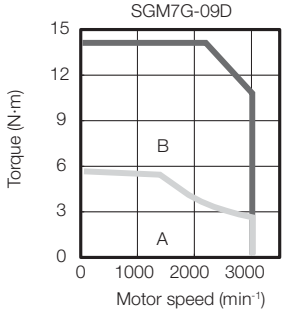
Standard Servomotors

A : Continuous duty zone
B : Intermittent duty zone

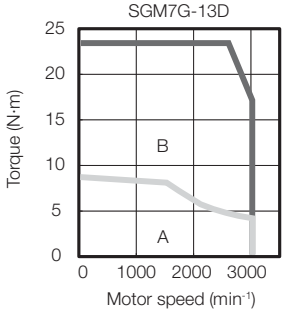
SGM7G-05D



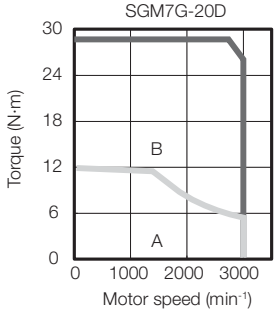
SGM7G-09D



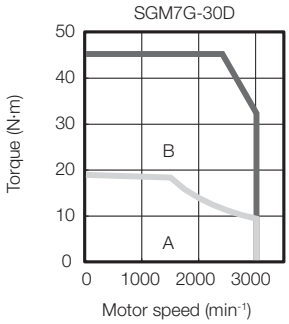
SGM7G-13D



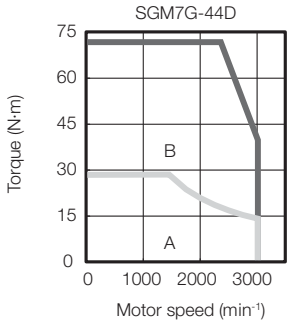
SGM7G-20D



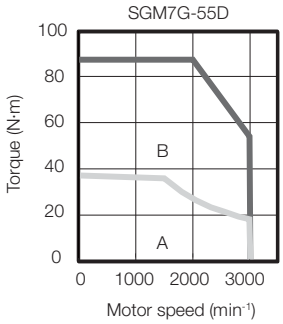
SGM7G-30D



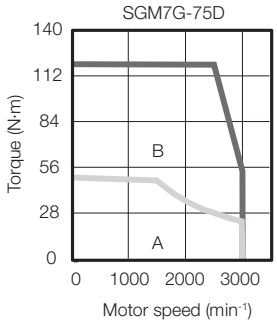
SGM7G-44D



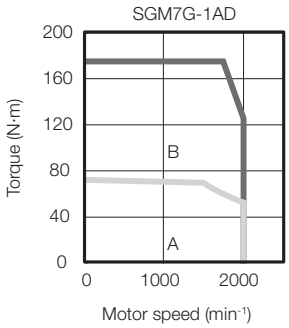
SGM7G-55D



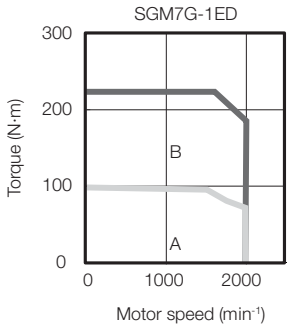
SGM7G-75D



SGM7G-1AD



SGM7G-1ED

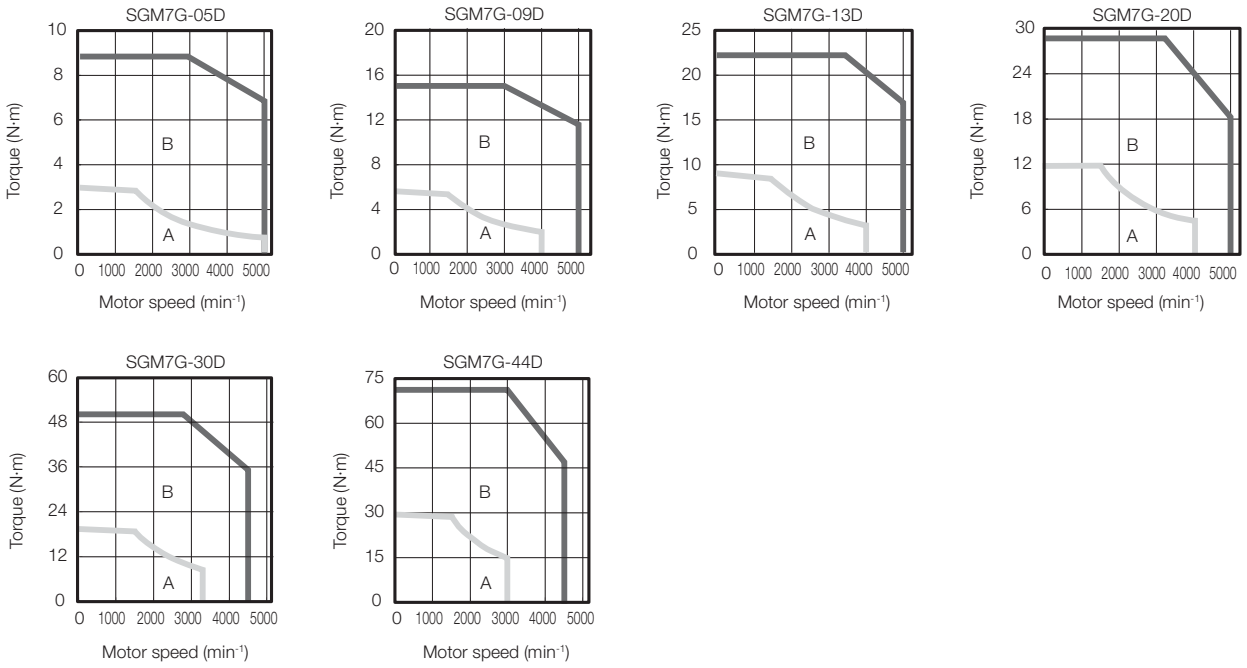


Note:

1. These values are for operation in combination with a SERVOPACK when the temperature of the armature winding is 20°C. These are typical values.
2. The characteristics in the intermittent duty zone depend on the power supply voltage. The intermittent duty zone in the graphs show the characteristics when a three-phase, 400-VAC power supply voltage is used.
3. If the effective torque is within the allowable range for the rated torque, the Servomotor can be used within the intermittent duty zone.
4. If you use a Servomotor Main Circuit Cable that exceeds 20 m, the intermittent duty zone in the torque-motor speed characteristics will become smaller because the voltage drop increases.

High-speed Servomotors

A : Continuous duty zone
B : Intermittent duty zone



Note:

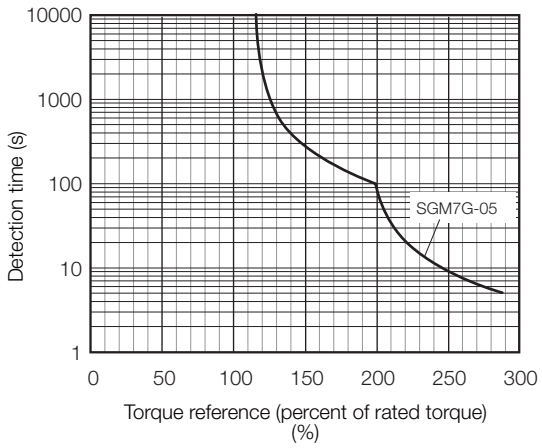
1. These values are for operation in combination with a SERVOPACK when the temperature of the armature winding is 20°C. These are typical values.
2. The characteristics in the intermittent duty zone depend on the power supply voltage. The intermittent duty zone in the graphs show the characteristics when a three-phase, 400-VAC power supply voltage is used.
3. If the effective torque is within the allowable range for the rated torque, the Servomotor can be used within the intermittent duty zone.
4. If you use a Servomotor Main Circuit Cable that exceeds 20 m, the intermittent duty zone in the torque-motor speed characteristics will become smaller because the voltage drop increases.

Servomotor Overload Protection Characteristics

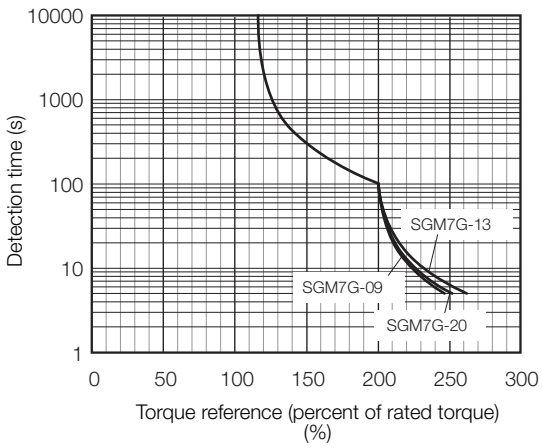
The overload detection level is set for hot start conditions with a Servomotor surrounding air temperature of 40 °C.

Standard Servomotors

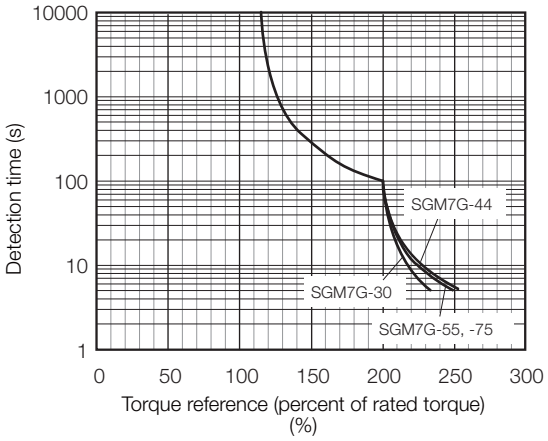
SGM7G-05



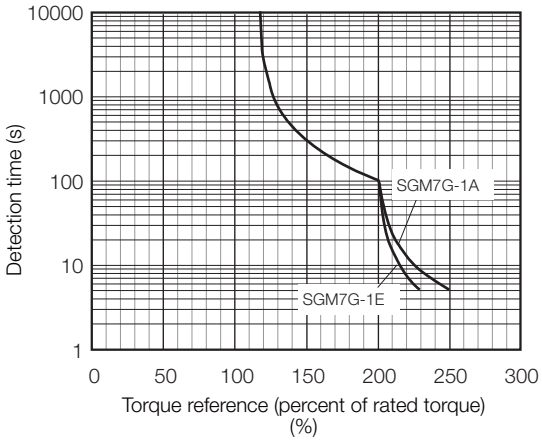
SGM7G-09, -13, and -20



SGM7G-30, -44, -55, and -75



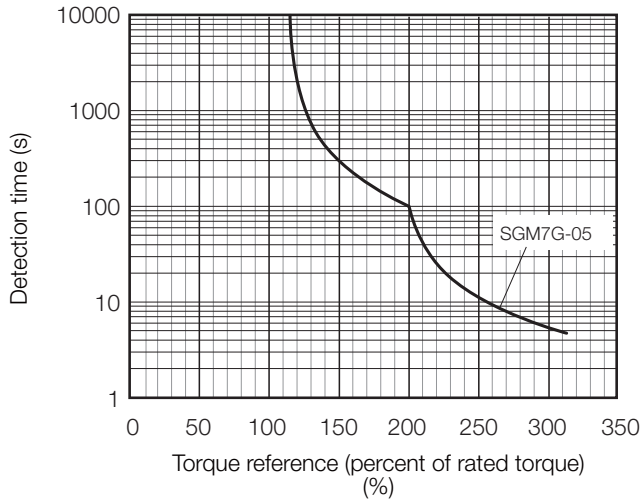
SGM7G-1A and -1E



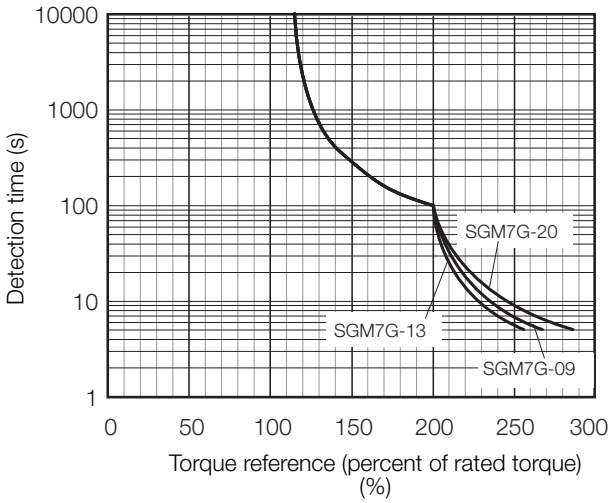
Note:
The overload protection characteristics do not mean that you can perform continuous duty operation with an output of 100% or higher. Use the Servomotor so that the effective torque remains within the continuous duty zone given in Motor Speed-Torque Characteristics.

High-speed Servomotors

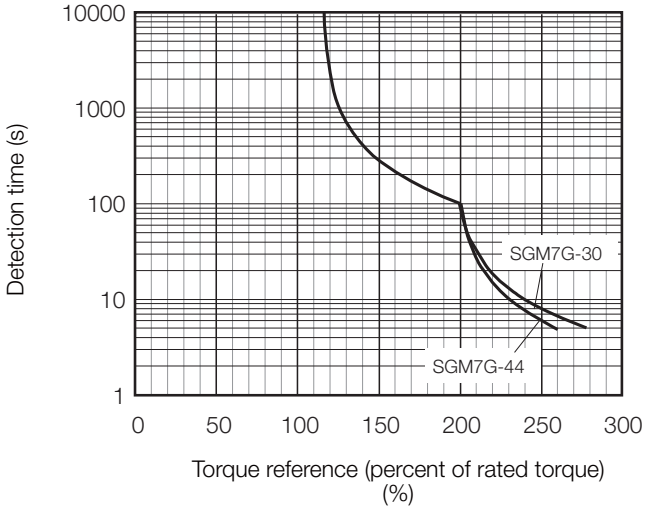
SGM7G-05



SGM7G-09, -13, and -20



SGM7G-30 and -44



Note:
The overload protection characteristics do not mean that you can perform continuous duty operation with an output of 100% or higher. Use the Servomotor so that the effective torque remains within the continuous duty zone given in Motor Speed-Torque Characteristics.

Load Moment of Inertia

The load moment of inertia indicates the inertia of the load. The larger the load moment of inertia, the worse the response. If the moment of inertia is too large, operation will become unstable.
The allowable size of the load moment of inertia (JL) for the Servomotor is restricted. Refer to Ratings of Rotary Serovmotors SGM7J. This value is provided strictly as a guideline and results depend on Servomotor driving conditions.
An Overvoltage Alarm (A.400) is likely to occur during deceleration if the load moment of inertia exceeds the allowable load moment of inertia. SERVOPACKs with a built-in regenerative resistor may generate a Regenerative Overload Alarm (A.320).

Perform one of the following steps if this occurs.

- Reduce the torque limit.
- Reduce the deceleration rate.
- Reduce the maximum motor speed.
- Install an external regenerative resistor if the alarm cannot be cleared using the above steps.

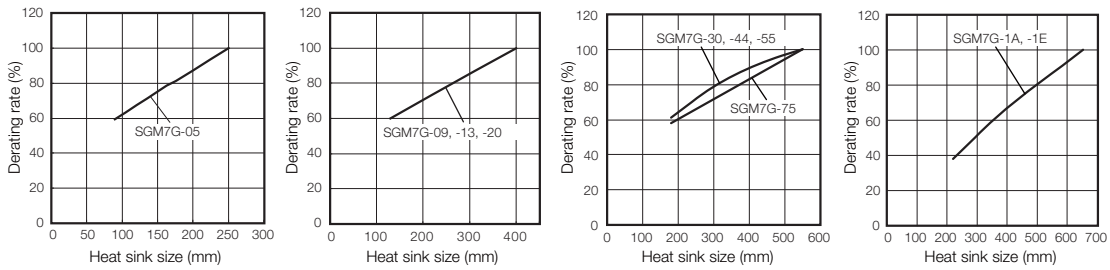
Servomotor Heat Dissipation Conditions

The Servomotor ratings are the continuous allowable values at a surrounding air temperature of 40°C when a heat sink is installed on the Servomotor. If the Servomotor is mounted on a small device component, the Servomotor temperature may rise considerably because the surface for heat dissipation becomes smaller. Refer to the following graphs for the relation between the heat sink size and derating rate.

Also, change the overload warning and overload alarm detection timing in advance based on the overload detection level of the motor. Refer to the section Servomotor Overload Protection Characteristics.

Note:
The derating rates are applicable only when the average motor speed is less than or equal to the rated motor speed.
If the average motor speed exceeds the rated motor speed, consult with your YASKAWA representative.

Important:
The actual temperature rise depends on how the heat sink (i. e., the Servomotor mounting section) is attached to the installation surface, what material is used for the Servomotor mounting section, and the motor speed. Always check the Servomotor temperature with the actual equipment.



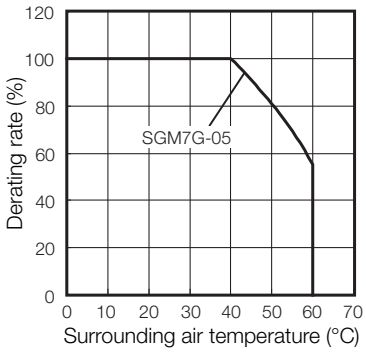
See Servomotor Ratings for more information.

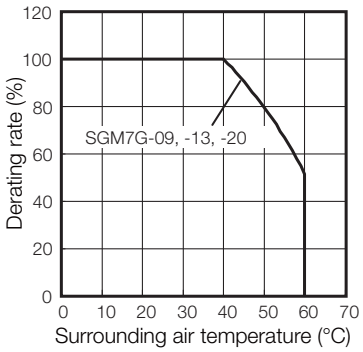
Applications Where the Surrounding Air Temperature of the Servomotor Exceeds 40°C

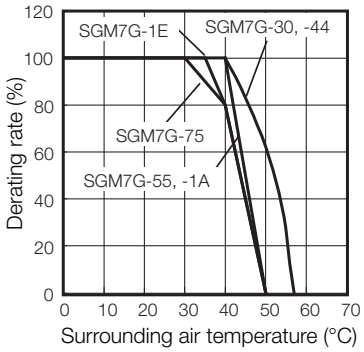
The Servomotor ratings are the continuous allowable values at a surrounding air temperature of 40°C. If you use a Servomotor at a surrounding air temperature that exceeds 40°C (60°C max.), apply a suitable derating rate from the following graphs.

Also, change the overload warning and overload alarm detection timing in advance based on the overload detection level of the motor. Refer to the section Servomotor Overload Protection Characteristics.

Note:
1. Use the combination of the SERVOPACK and Servomotor so that the derating conditions are satisfied for both the SERVOPACK and Servomotor.
2. The derating rates are applicable only when the average motor speed is less than or equal to the rated motor speed. If the average motor speed exceeds the rated motor speed, consult with your YASKAWA representative.





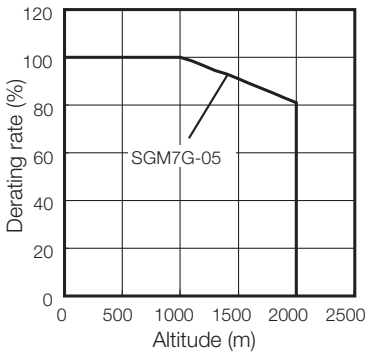


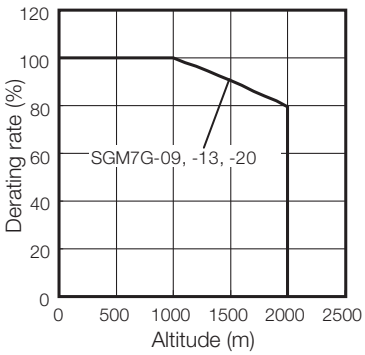
Applications Where the Altitude of the Servomotor Exceeds 1,000 m

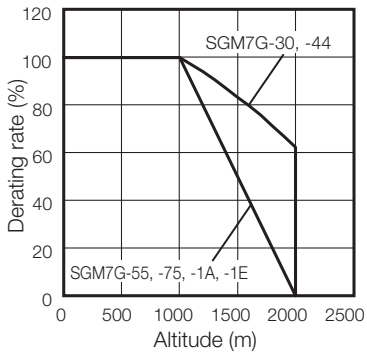
The Servomotor ratings are the continuous allowable values at an altitude of 1,000 m or less. If you use a Servomotor at an altitude that exceeds 1,000 m (2,000 m max.), the heat dissipation effect of the air is reduced. Apply the appropriate derating rate from the following graphs.

Also, change the overload warning and overload alarm detection timing in advance based on the overload detection level of the motor. Refer to the section Servomotor Overload Protection Characteristics.

Note:
1. Use the combination of the SERVOPACK and Servomotor so that the derating conditions are satisfied for both the SERVOPACK and Servomotor.
2. The derating rates are applicable only when the average motor speed is less than or equal to the rated motor speed. If the average motor speed exceeds the rated motor speed, consult with your YASKAWA representative.

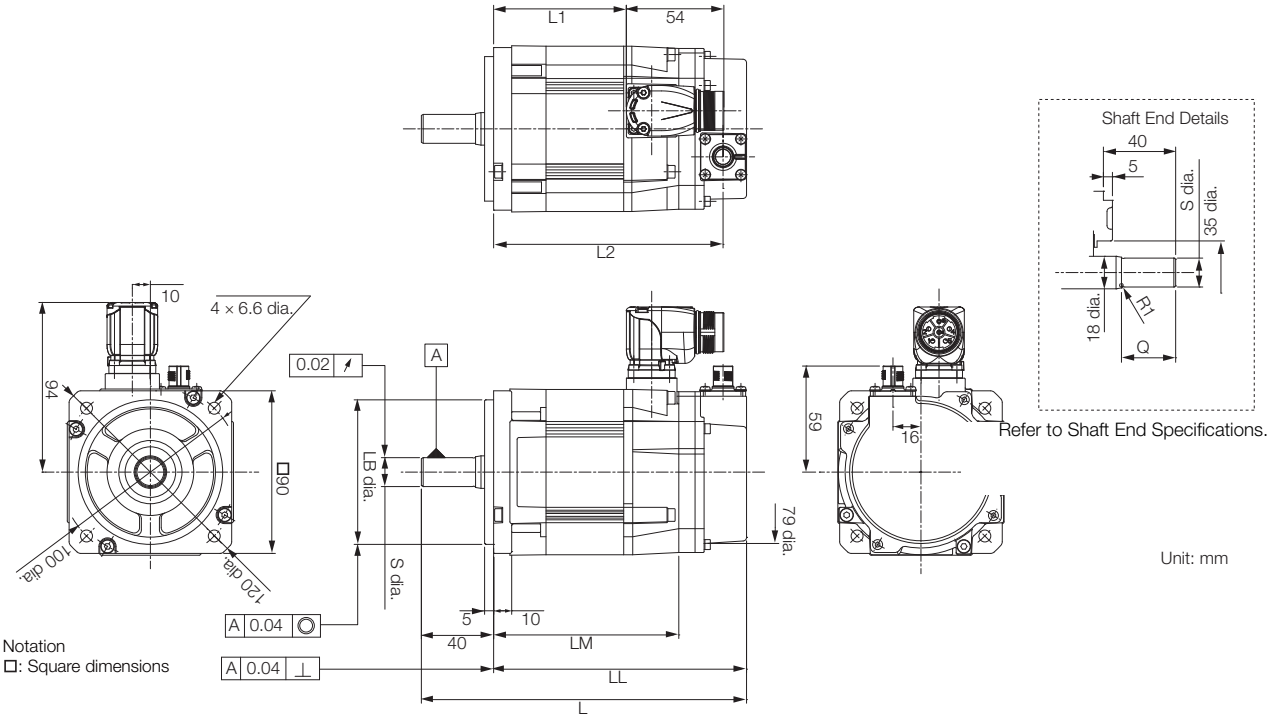






External Dimensions

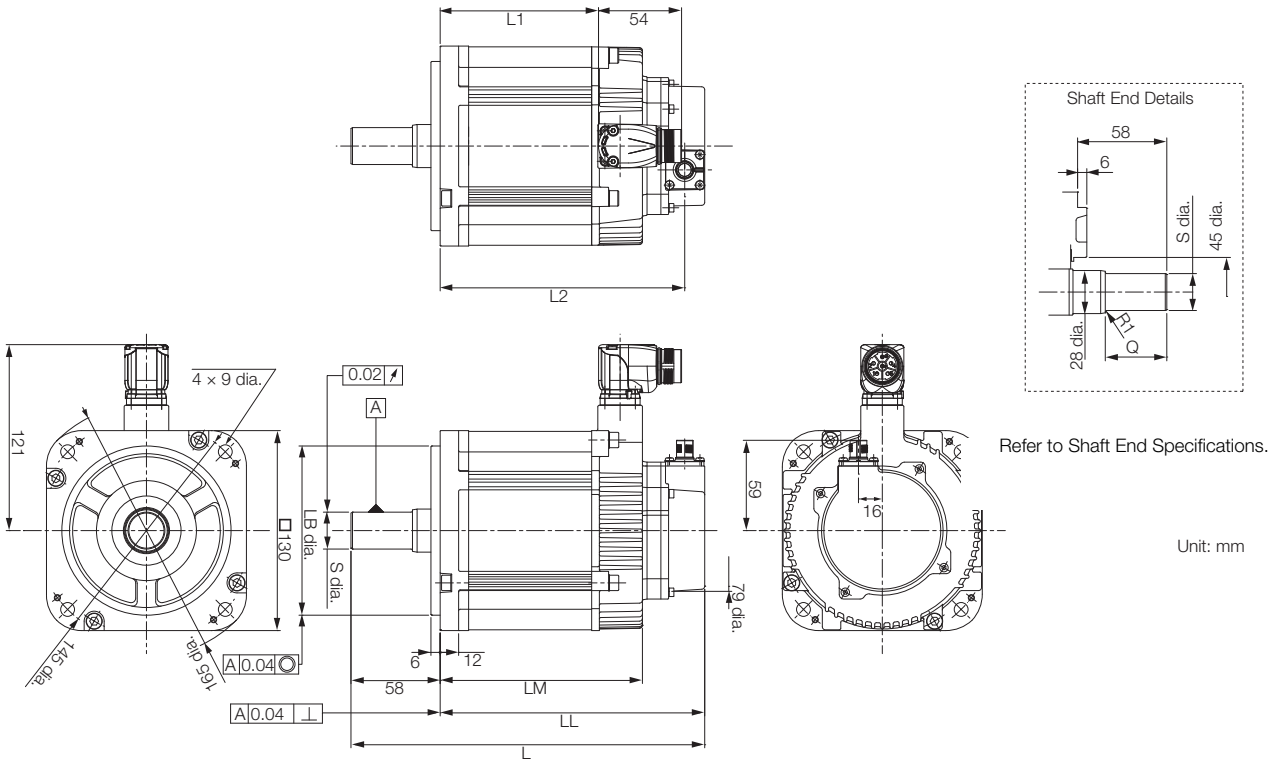
SGM7G-05



Model SGM7A-	L	LL	LM	L1	L2	LB	Shaft End Dimensions		Approx. Mass [kg]
							S	Q	
05D□F2□	181 (214)	141 (174)	103 (136)	74	127 (161)	$80^{0}_{-0.030}$	$16^{0}_{-0.011}$	30	3.3 (4.3)

Note:
1. The values in parentheses are for Servomotors with Holding Brakes.
2. Refer to the section Shaft End Specifications.
3. Refer to the section Connector Specifications.

SGM7G-09, -13, -20



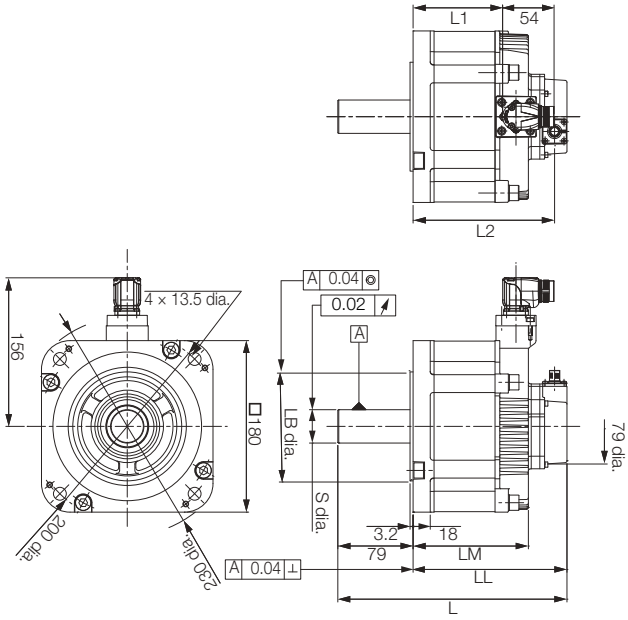
Refer to Shaft End Specifications.

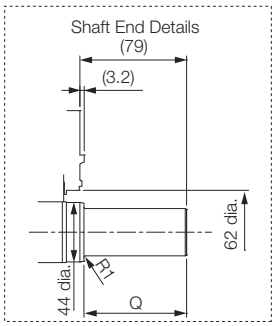
Unit: mm

Model SGM7G-	L	LL	LM	L1	L2	LB	Shaft End Dimensions		Approx. Mass [kg]
							S	Q	
09D□FS□	197 (233)	139 (175)	101 (137)	69	125 (161)	$110^{0}_{-0.035}$	$19^{0}_{-0.013}$	40	5.6 (7.6)
13D□FS□	213 (249)	155 (191)	117 (153)	85	141 (177)	$110^{0}_{-0.035}$	$22^{0}_{-0.013}$	40	7.2 (9.1)
20D□F2□	231 (267)	173 (209)	135 (171)	103	159 (195)	$110^{0}_{-0.035}$	$24^{0}_{-0.013}$	40	8.7 (11.1)

Note:
1. The values in parentheses are for Servomotors with Holding Brakes.
2. Servomotors with Dust Seals have the same dimensions.
3. Refer to the section Shaft End Specifications.
Refer to the section Connector Specifications SGM7G.

SGM7G-30, -44, -55 and -75





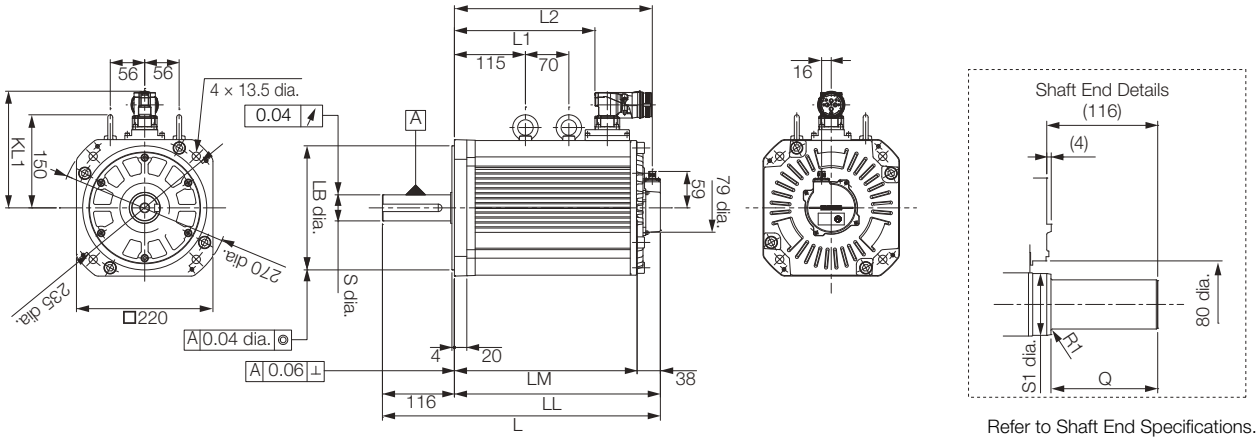
Refer to Shaft End Specifications.

Unit: mm

Model SGM7G-	L	LL	LM	L1	L2	LB	Shaft End Dimensions		Approx. Mass [kg]
							S	Q	
30D□F2□	241 (289)	162 (210)	124 (172)	94	149 (197)	$114.3^{0}_{-0.035}$	$35^{+0.01}_{0}$	76	13.6 (19.6)
44D□F2□	265 (313)	186 (234)	148 (196)	118	173 (221)	$114.3^{0}_{-0.025}$	$35^{+0.01}_{0}$	76	18.0 (24.0)
44D□R2□	265 (313)	186 (234)	148 (196)	112	173 (221)	$114.3^{0}_{-0.025}$	$35^{+0.01}_{0}$	76	18.0 (24.0)
55D□F2□	336 (380)	223 (267)	185 (229)	143	210 (254)	$114.3^{0}_{-0.025}$	$42^{0}_{-0.016}$	110	22.0 (28.0)
75D□F2□	382 (426)	269 (313)	231 (275)	189	256 (300)	$114.3^{0}_{-0.025}$	$42^{0}_{-0.016}$	110	30.0 (35.5)

Note:
1. The values in parentheses are for Servomotors with Holding Brakes.
2. Servomotors with Dust Seals have the same dimensions.
3. Refer to the section Shaft End Specifications.
Refer to the section Connector Specifications.

SGM7G-1A and -1E



Refer to Shaft End Specifications.

Unit: mm

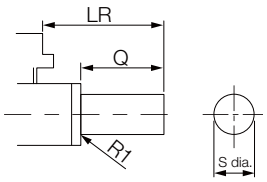
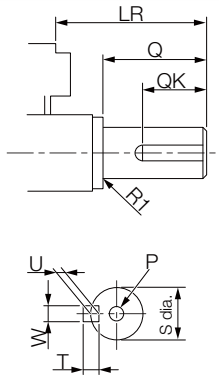
Model SGM7G-	L	LL	LM	L1	L2	LB	KL1	Shaft End Dimensions			Approx. Mass [kg]
								S	S1	Q	
1AD□F2□	449 (500)	333 (384)	295 (346)	227	319 (371)	$200^{0}_{-0.046}$	188	$42^{0}_{-0.016}$	50	110	57.5 (65.5)
1ED□F2□	511 (600)	395 (484)	357 (446)	289	382 (470)	$200^{0}_{-0.046}$	188	$55^{+0.030}_{+0.011}$	60	110	67.5 (79.5)

Note:
1. The values in parentheses are for Servomotors with Holding Brakes.
2. Servomotors with Dust Seals have the same dimensions.
3. Refer to the section Shaft End Specifications.
Refer to the section Connector Specifications.

Shaft End Specifications

SGM7G-□□□□□□□

Code	Specification
2 or S*	Straight without key
6 or K*	Straight with key and tap for one location (Key slot is JIS B1301-1996 fastening type.)

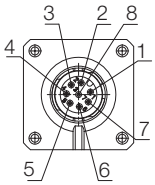
Shaft End Details		Servomotor Model SGM7G-									
		05	09	13	20	30	44	55	75	1A	1E
Code: 2 or S* (Straight without Key)											
	LR	40	58	58	58	79		113		116	
	Q	30	40	40	40	76				110	
	S	$16^{0}_{-0.011}$	$19^{0}_{-0.013}$	$22^{0}_{-0.013}$	$24^{0}_{-0.013}$	$35^{+0.01}_{0}$		$42^{0}_{-0.016}$		$42^{0}_{-0.016}$	$55^{+0.030}_{+0.011}$
Code: 6 or K* (Straight with Key and Tap)											
	LR	40	58	58	58	79		113		116	
	Q	30	40	40	40	76				110	
	QK	20	25	25	25	60				90	
	S	$16^{0}_{-0.011}$	$19^{0}_{-0.013}$	$22^{0}_{-0.013}$	$24^{0}_{-0.013}$	$35^{+0.01}_{0}$		$42^{0}_{-0.016}$		$42^{0}_{-0.016}$	$55^{+0.030}_{+0.011}$
	W	5	5	6	8		10			12	16
	T	5	5	6	7			8			10
	U	3	3	3.5	4			5			6
	P	M5 screw, Depth: 12				M12 screw, Depth: 25		M16 x 32L			M20 x 40L

* The code for the shaft end depends on the model:
SGM7G-05, -20, -30, -44, -55, -75, -1A, or -1E: 2 or 6
SGM7G-09 or -13: S or K

Connector Specifications

SGM7G-05D□F to -44D□F and SGM7G-05D□R to -30D□R

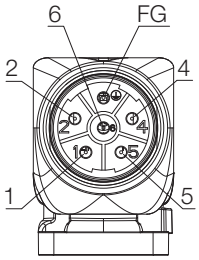
- Encoder Connector Specifications



Receptacle
Size: M12
Part number: 1419959
Model: SACC-MSQ-M12MS-25-3,2 SCO
Manufacturer: Phoenix Contact

1	PG 5V
2	PG 0V
3	FG
4	BAT (+)
5	BAT (-)
6	Data (+)
7	Data (-)
8	Empty
Housing	Shield

- Servomotor Connector Specifications

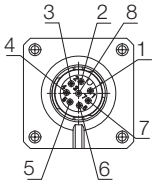


Receptacle
Size: M23
Part number: 1617905
Model: SF-5EP1N8AAD00S
Manufacturer: Phoenix Contact

1	V
2	(Brake)
4	(Brake)
5	U
6	W
FG	FG
Housing	Shield

SGM7G-55D□F to -1ED□F and SGM7G-44D□R

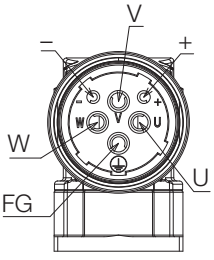
- Encoder Connector Specifications



Receptacle
Size: M12
Part number: 1419959
Model: SACC-MSQ-M12MS-25-3,2 SCO
Manufacturer: Phoenix Contact

1	PG 5V
2	PG 0V
3	FG
4	BAT (+)
5	BAT (-)
6	Data (+)
7	Data (-)
8	Empty
Housing	Shield

- Servomotor Connector Specifications



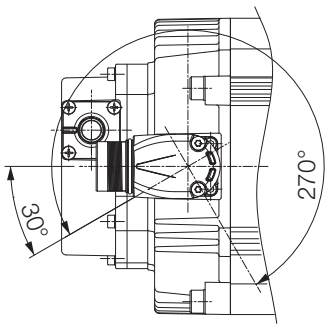
Receptacle
Size: M40
Part number: 1607927
Model: SM-5EPWN8AAD00S
Manufacturer: Phoenix Contact

U	U
V	V
W	W
+	(Brake)
7	(Brake)
FG	FG
Housing	Shield

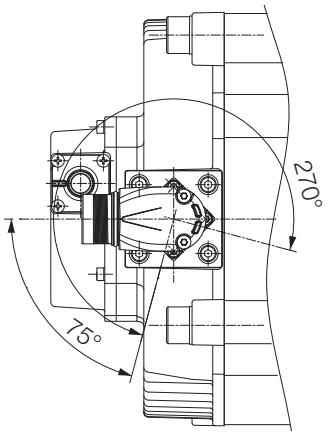
Servomotor Connector Rotational Angle

Allowable number of rotations: 10

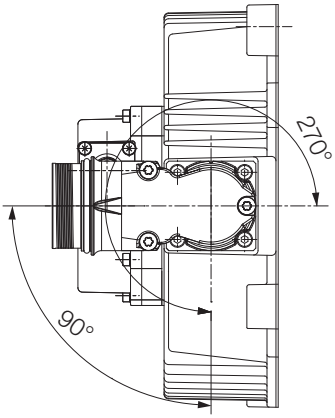
SGM7G-05D□□ to -20D□□



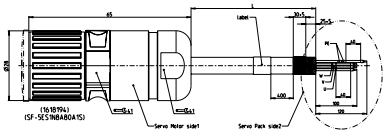
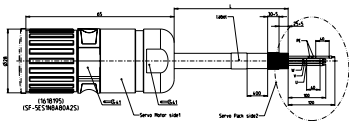
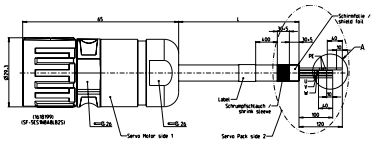
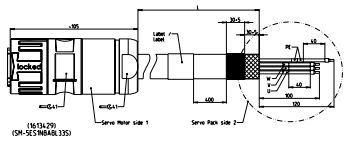
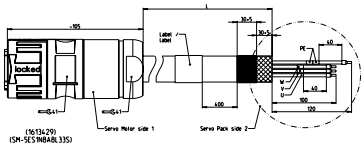
SGM7G-30D□□, -44D□F



SGM7G-44D□R, -55D□F, -75D□F, -1AD□F and -1AD□F

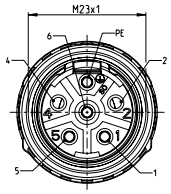


Power Cables for rotary servomotors without holding brake

Servomotor Model	Cable & connector type	Length	Order No.	Specification
SGM7G-05 to -20 SGM7G-05 to -09 High Speed	Flexible Power cable 4 x 1.5 mm² with M23 connector	3 m	JZSP-C7M144-03-E-G6	
		5 m	JZSP-C7M144-05-E-G6	
		10 m	JZSP-C7M144-10-E-G6	
		15 m	JZSP-C7M144-15-E-G6	
		20 m	JZSP-C7M144-20-E-G6	
SGM7G-30 SGM7G-13 to -20 High Speed	Flexible Power cable 4 x 2.5 mm² with M23 connector	3 m	JZSP-C7M154-03-E-G6	
		5 m	JZSP-C7M154-05-E-G6	
		10 m	JZSP-C7M154-10-E-G6	
		15 m	JZSP-C7M154-15-E-G6	
		20 m	JZSP-C7M154-20-E-G6	
SGM7G-44 SGM7G-30 High Speed	Flexible Power cable 4 x 4 mm² with M23 connector	3 m	JZSP-C7M164-03-E-G6	
		5 m	JZSP-C7M164-05-E-G6	
		10 m	JZSP-C7M164-10-E-G6	
		15 m	JZSP-C7M164-15-E-G6	
		20 m	JZSP-C7M164-20-E-G6	
SGM7G-55 to -75 SGM7G-44 High Speed	Flexible Power cable 4 x 6.0 mm² with M40 connector	3 m	JZSP-C7M175-03-E-G6	
		5 m	JZSP-C7M175-05-E-G6	
		10 m	JZSP-C7M175-10-E-G6	
		15 m	JZSP-C7M175-15-E-G6	
		20 m	JZSP-C7M175-20-E-G6	
SGM7G-1A to -1E	Flexible Power cable 4 x 10.0 mm² with M40 connector	3 m	JZSP-C7M185-03-E-G6	
		5 m	JZSP-C7M185-05-E-G6	
		10 m	JZSP-C7M185-10-E-G6	
		15 m	JZSP-C7M185-15-E-G6	
		20 m	JZSP-C7M185-20-E-G6	

Pin Layout for Power Cables for rotary servomotors without holding brake

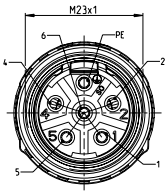
JZSP-C7M144-xx-E-G6



Connector: SF-5ES1N8A80A1S (1618194)
From Phoenix Contact GmbH & Co. KG

Pin No.	Function	Wire Color
1	V	Black wire 2
2	n.c.	n.c.
4	n.c.	n.c.
5	U	Black wire 1
6	W	Black wire 3
PE (3)	PE	Green-yellow
Housing		Shield

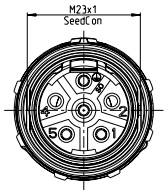
JZSP-C7M154-xx-E-G6



Connector: SF-5ES1N8A80A2S (1618195)
From Phoenix Contact GmbH & Co. KG

Pin No.	Function	Wire Color
1	V	Black wire 2
2	n.c.	n.c.
4	n.c.	n.c.
5	U	Black wire 1
6	W	Black wire 3
PE (3)	PE	Green-yellow
Housing		Shield

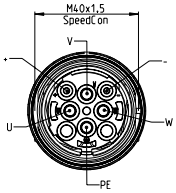
JZSP-C7M164-xx-E-G6



Connector: SF-5ES1N8A80A3S (1618199)
From Phoenix Contact GmbH & Co. KG

Pin No.	Function	Wire Color
1	V	Black wire 2
2	n.c.	n.c.
4	n.c.	n.c.
5	U	Black wire 1
6	W	Black wire 3
PE (3)	PE	Green-yellow
Housing		Shield

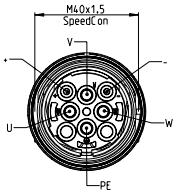
JZSP-C7M175-xx-E-G6



Connector: SM-5ES1N8A8L32S (1613428)
From Phoenix Contact GmbH & Co. KG

Pin No.	Function	Wire Color
V	V	Black wire 2
+	n.c.	n.c.
-	n.c.	n.c.
U	U	Black wire 1
W	W	Black wire 3
PE	PE	Green-yellow
Housing		Shield

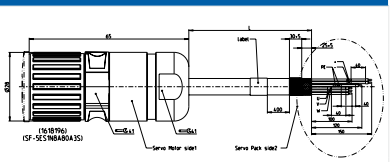
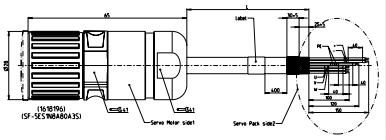
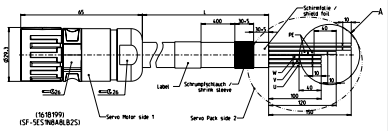
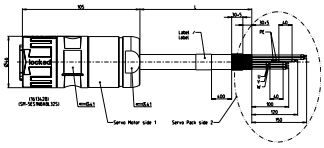
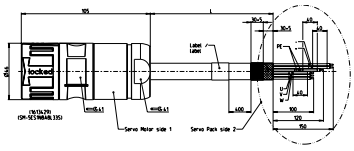
JZSP-C7M185-xx-E-G6



Connector: SM-5ES1N8A8L33S (1613429)
From Phoenix Contact GmbH & Co. KG

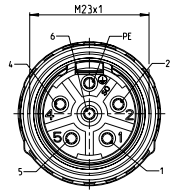
Pin No.	Function	Wire Color
V	V	Black wire 2
+	n.c.	n.c.
-	n.c.	n.c.
U	U	Black wire 1
W	W	Black wire 3
PE	PE	Green-yellow
Housing		Shield

Power Cables for rotary servomotors with holding brake

Servomotor Model	Cable & connector type	Length	Order No.	Specification
SGM7G-05 to -20 SGM7G-05 to -09 High Speed	Flexible Power cable 4 x 1.5 mm² & 2 x 1.5 mm² for brake with M23 connector	3 m	JZSP-C7M344-03-E-G6	
		5 m	JZSP-C7M344-05-E-G6	
		10 m	JZSP-C7M344-10-E-G6	
		15 m	JZSP-C7M344-15-E-G6	
		20 m	JZSP-C7M344-20-E-G6	
SGM7G-30 SGM7G-13 to -20 High Speed	Flexible Power cable 4 x 2.5 mm² & 2 x 1.5 mm² for brake with M23 connector	3 m	JZSP-C7M354-03-E-G6	
		5 m	JZSP-C7M354-05-E-G6	
		10 m	JZSP-C7M354-10-E-G6	
		15 m	JZSP-C7M354-15-E-G6	
		20 m	JZSP-C7M354-20-E-G6	
SGM7G-44 SGM7G-30 High Speed	Flexible Power cable 4 x 4 mm² & 2 x 1.5 mm² for brake with M23 connector	3 m	JZSP-C7M364-03-E-G6	
		5 m	JZSP-C7M364-05-E-G6	
		10 m	JZSP-C7M364-10-E-G6	
		15 m	JZSP-C7M364-15-E-G6	
		20 m	JZSP-C7M364-20-E-G6	
SGM7G-55 to -75 SGM7G-44 High Speed	Flexible Power cable 4 x 6.0 mm² & 2 x 1.5 mm² for brake with M40 connector	3 m	JZSP-C7M375-03-E-G6	
		5 m	JZSP-C7M375-05-E-G6	
		10 m	JZSP-C7M375-10-E-G6	
		15 m	JZSP-C7M375-15-E-G6	
		20 m	JZSP-C7M375-20-E-G6	
SGM7G-1A to -1E	Flexible Power cable 4 x 10.0 mm² & 2 x 1.5 mm² for brake with M40 connector	3 m	JZSP-C7M385-03-E-G6	
		5 m	JZSP-C7M385-05-E-G6	
		10 m	JZSP-C7M385-10-E-G6	
		15 m	JZSP-C7M385-15-E-G6	
		20 m	JZSP-C7M385-20-E-G6	

Pin Layout for Power Cables for rotary servomotors with holding brake

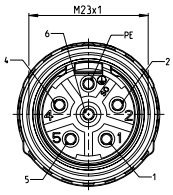
JZSP-C7M344-xx-E-G6



Connector: SF-5ES1N8A80A3S (1618196)
From Phoenix Contact GmbH & Co. KG

Pin No.	Function	Wire Color
1	V	Black wire 2
2	+	Black
4	-	White
5	U	Black wire 1
6	W	Black wire 3
PE (3)	PE	Green-yellow
Housing		Shield

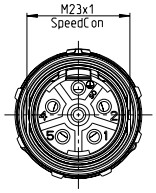
JZSP-C7M354-xx-E-G6



Connector: SF-5ES1N8A80A3S (1618195)
From Phoenix Contact GmbH & Co. KG

Pin No.	Function	Wire Color
1	V	Black wire 2
2	+	Black
4	-	White
5	U	Black wire 1
6	W	Black wire 3
PE (3)	PE	Green-yellow
Housing		Shield

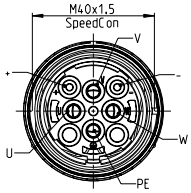
JZSP-C7M364-xx-E-G6



Connector: SF-5ES1N8A8LB2S (1618199)
From Phoenix Contact GmbH & Co. KG

Pin No.	Function	Wire Color
1	V	Black wire 2
2	-	Black (L=150)
4	-	Black (L=150)
5	U	Black wire 1
6	W	Black wire 3
PE (3)	PE	Green-yellow
Housing		Shield

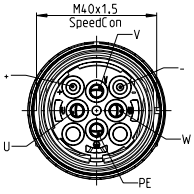
JZSP-C7M375-xx-E-G6



Connector: SM-5ES1N8A8L32S (1613428)
From Phoenix Contact GmbH & Co. KG

Pin No.	Function	Wire Color
V	V	Black wire 2
+	+	Black wire 1.50
-	-	Black wire 1.50
U	U	Black wire 1
W	W	Black wire 3
PE (3)	PE	Green-yellow
Housing		Shield

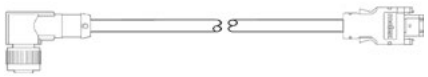
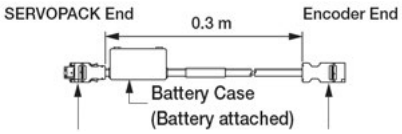
JZSP-C7M385-xx-E-G6



Connector: SM-5ES1N8A8L33S (1613429)
From Phoenix Contact GmbH & Co. KG

Pin No.	Function	Wire Color
V	V	Black wire 2
+	+	Black
-	-	White
U	U	Black wire 1
W	W	Black wire 3
PE (3)	PE	Green-yellow
Housing		Shield

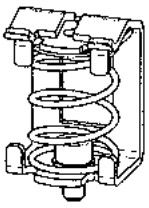
Encoder cables for rotary servomotors

Cable & connector type	Length	Sigma-7 cable for absolute encoder*	Sigma-7 cable for incremental encoder	Appearance
Flexible Encoder cable with straight connector M12	3m	JZSP-C7PA2M-03-E-G☐	JZSP-C7PI2M-03-E-G6	
	5m	JZSP-C7PA2M-05-E-G☐	JZSP-C7PI2M-05-E-G6	
	10m	JZSP-C7PA2M-10-E-G☐	JZSP-C7PI2M-10-E-G6	
	15m	JZSP-C7PA2M-15-E-G☐	JZSP-C7PI2M-15-E-G6	
	20m	JZSP-C7PA2M-20-E-G☐	JZSP-C7PI2M-20-E-G6	
Flexible Encoder cable with angled connector M12	3m	JZSP-C7PA2N-03-E-G☐	JZSP-C7PI2N-03-E-G6	
	5m	JZSP-C7PA2N-05-E-G☐	JZSP-C7PI2N-05-E-G6	
	10m	JZSP-C7PA2N-10-E-G☐	JZSP-C7PI2N-10-E-G6	
	15m	JZSP-C7PA2N-15-E-G☐	JZSP-C7PI2N-15-E-G6	
	20m	JZSP-C7PA2N-20-E-G☐	JZSP-C7PI2N-20-E-G6	
Sigma-7 Extension for Encoder cable with Connectors length 0.3m for Abs. Encoder	0.3m	JZSP-CSP12-E-G5	-	

* Sigma-7 cables for absolute encoders have a battery case (Battery attached).
Currently under preparation.

Motor Connection Shielding Clamp

Shielding clamp mountable on Sigma-7 400V SERVOPACKs up to 15kW.
Contact your YASKAWA representative for more information.

SERVOPACK Model	Order No.	Specification
Sigma-7 400V up to 3.0kW	KLBUE 4-13.5_SC	
Sigma-7 400V from 5kW up to 7.5kW	KLBUE 10-20_SC	
Sigma-7 400V for 11kW & 15kW	KLBUE 15-32_SC	

SGLFW2

- Model with F-type iron core
- Rated force: 45 N - 2,520 N
  Peak force: 135 N - 7,560 N